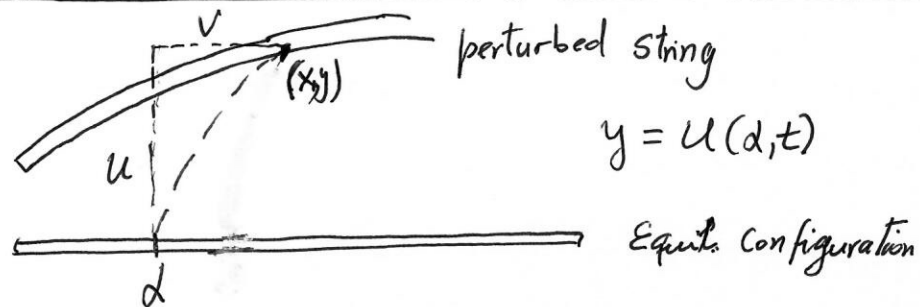
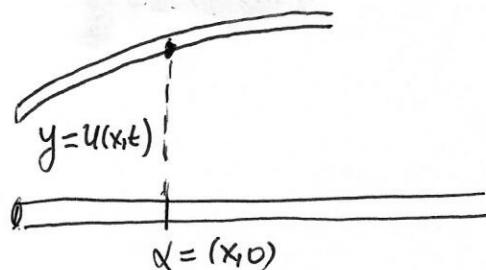


4.2 Derivation of a Vertically Vibrating String.



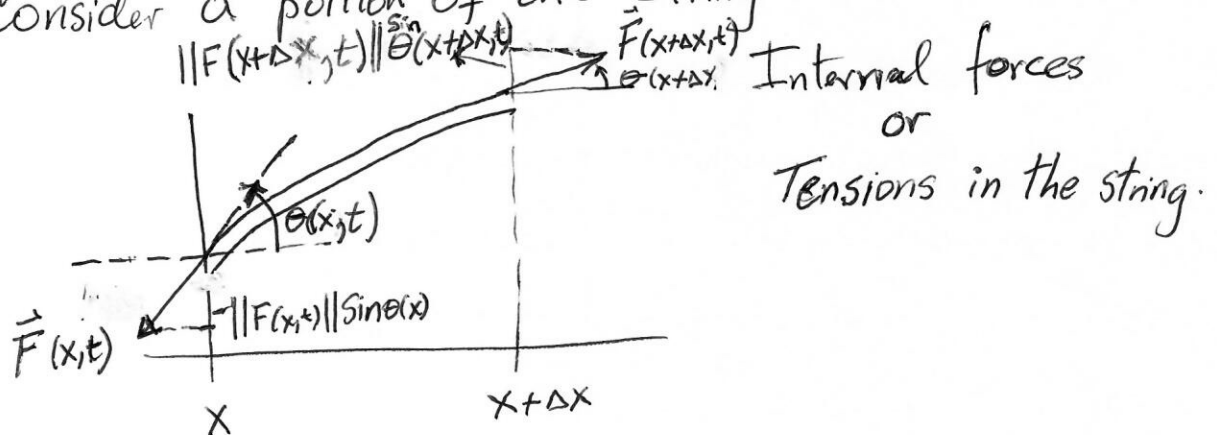
Assumption: $|u| \ll 1$ Very small. It can be neglected.
 Since slope of perturbed string is small

The previous assumption leads to entire vertical motion.



Application of Newton 2nd Law:

Consider a portion of the string



$$[Q(x,t)] = \frac{F}{m}$$

If $\|\vec{F}(x,t)\| = T(x,t)$, $Q(x,t)$: Vertical component of body forces/mass

Then $m \vec{a} = \sum \vec{F}$

$\rho_0(x)$: Linear density (mass)
 $[\rho_0] = \frac{M}{L}$

implies

$$\left[\begin{array}{l} \text{Newton 2nd Law} \\ \text{Applied to} \\ \text{portion of string} \\ [x, x+\Delta x] \end{array} \right] \int_x^{x+\Delta x} \rho_0(x) \frac{\partial^2 u}{\partial t^2}(x,t) dx = T(x+\Delta x, t) \sin \theta(x+\Delta x, t) - T(x, t) \sin \theta(x, t) + \int_x^{x+\Delta x} \rho_0(x) Q(x, t) dx$$

Using the Mean Value Theorem for integrals:

$$\bar{x} \in (x, x+\Delta x)$$

$$\rho_0(\bar{x}) \frac{\partial^2 u}{\partial t^2}(\bar{x}, t) \Delta x = T(x+\Delta x, t) \sin \theta(x+\Delta x, t) - T(x, t) \sin \theta(x) + \rho_0(\bar{x}) Q(\bar{x}, t) \Delta x$$

Dividing by $\rho_0(\bar{x}) \Delta x$ and taking $\lim_{\Delta x \rightarrow 0}$.

$$\rho_0(x) \frac{\partial^2 u}{\partial t^2}(x, t) = \frac{\partial}{\partial x} (T \sin \theta)(x, t) + \rho_0(x) Q(x, t)$$

Now, for small angles θ .

$$\frac{\partial u}{\partial x} = \tan \theta = \frac{\sin \theta}{\cos \theta} \approx \sin \theta$$

Then, we obtain

$$\boxed{\rho_0(x) \frac{\partial^2 u(x,t)}{\partial t^2} = \frac{\partial}{\partial x} \left(T \frac{\partial u}{\partial x} \right) + \rho_0(x) Q(x,t)} \quad (3.1)$$

Assumption: Perfectly elastic string and θ small

then, $T(x,t) \approx T_0$ constant.

and

$$\boxed{\rho_0(x) u_{tt}(x,t) = T_0 u_{xx}(x,t) + \rho_0(x) Q(x,t)} \quad (3.2)$$

If $Q(x,t) = -g$ and $\rho_0 g \ll |T_0 u_{xx}|$

then this body force can be neglected.

and we arrive to

$$\boxed{\frac{\partial^2 u}{\partial t^2} = \frac{T_0}{\rho_0(x)} \frac{\partial^2 u}{\partial x^2} = C(x) \frac{\partial^2 u}{\partial x^2}}$$

One-dimensional
Wave equation.

(3.3)

Show that $[C(x)] = \frac{L}{t^2}$.

If $Q(x,t)=0$, then

$$\frac{\partial^2 u}{\partial t^2} = C(x)^2 \frac{\partial^2 u}{\partial x^2}$$

→ wave speed

$$C(x)^2 \equiv T_0 / \rho_0(x) \quad \left[\frac{T_0}{\rho_0} \right] = \frac{M \frac{L}{t^2}}{\frac{M}{L}} = \frac{L^2}{t^2} \checkmark$$

If string is uniform then C is constant.

One-dimensional wave equation.

4.3

Boundary conditions:

a) Fixed ends: $\begin{cases} u(0,t) = 0 \\ u(L,t) = 0 \end{cases}$

b) Prescribed Variations: $\begin{cases} u(0,t) = f(t) \\ u(L,t) = g(t) \end{cases}$

c) Free ends: $u_x(0,t) = 0, u_x(L,t) = 0$

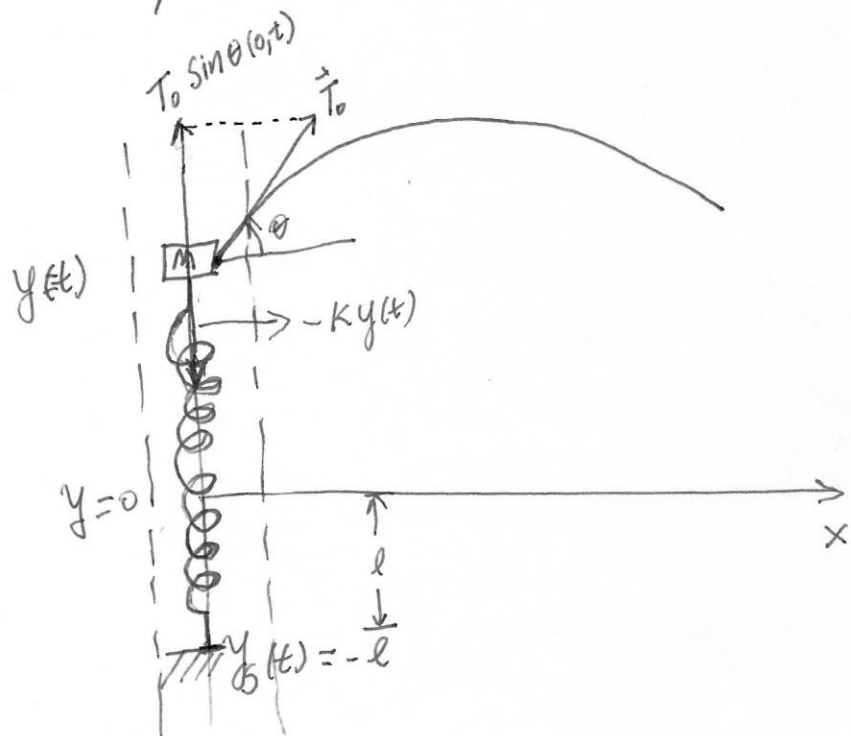
Initial conditions:

$$u(x,0) = \phi(x)$$

$$u_t(x,0) = \psi(x)$$

Why two IC's?

c) Left end $x=0$ is attached to a Spring-mass system.



l : Spring natural length.

$$y(t) = u(0,t). \quad \underline{\text{B.C.}}$$